

# Andrew Lee

Last updated on Oct 1, 2024

📍 Davis, CA, 95616 ✉ awclee@ucdavis.edu 🌐 andrewclee.github.io 📄 andrewclee

## Education

---

### University of California, Davis

*Ph.D. in Computer Science*

- Advisor: Iman Soltani, Ph.D.

May 2023 - Present

Davis, CA

### University of California, Davis

*Master of Science in Computer Science* (changed degree objective to Ph.D.)

Sep 2021 - May 2023

Davis, CA

### Hanyang University

*Bachelor of Science in Mechanical Engineering*

- Undergraduate Thesis: Compact Motor-Driven Walk-Support Device for Reducing Muscle Load
- Advisor: Sukkee Um, Ph.D.

Feb 2020

Seoul, South Korea

## Experience

---

### Laboratory for AI, Robotics and Automation (LARA)

*Graduate Student Researcher*

Jun 2022 - Present

Davis, CA

- Led multiple robotics research projects [1, 2] utilizing the *ALOHA 2* bimanual manipulation setup.
- Contributed to several Caltrans-funded projects, including the development of an ADA ramp detection and measurement system and an Infrared Advanced Driver Assistance System (IR-ADAS) for enhanced safety in low-visibility conditions.

## Publications

---

‡ indicates equal contribution.

[2] Ian Chuang<sup>‡</sup>, Andrew Lee<sup>‡</sup>, Dechen Gao, Iman Soltani. **Active Vision Might Be All You Need: Exploring Active Vision in Bimanual Robotic Manipulation.** *arXiv preprint. 2024.*

[1] Andrew Lee, Ian Chuang, Ling-Yuan Chen, Iman Soltani. **InterACT: Inter-dependency Aware Action Chunking with Hierarchical Attention Transformers for Bimanual Manipulation.** *Conference on Robot Learning (CoRL). 2024.*

## Projects

---

### ADA-Ramp

*Caltrans*

- Developed and implemented a comprehensive ramp detection and measurement pipeline, converting large-scale raw point cloud data into accurate bounding boxes, slope calculations, and width measurements.
- Utilized Faster R-CNN for precise ADA ramp detection within the pipeline.

### IR-ADAS

*Caltrans*

- Developed an Infrared Advanced Driver Assistance System (ADAS) to enhance safety and operational efficiency for emergency tow trucks and snowplows in low-visibility environments.
- Implemented the system on Jetson Nano Orin using TensorRT and YOLOv7, enabling real-time obstacle detection and hazard avoidance for improved situational awareness.

## Awards and Honors

---

2024 Computer Science Graduate Group (GGCS) Summer Ph.D. Fellowship

May 2024